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Benha University

#### **GEOMATICS ENGINEERING DEPARTMENT**

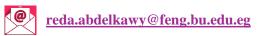
**SECOND YEAR GEOMATICS** 

GEODESY 2 (GED209)

**LECTURE NO: 10** 

#### **ESTABLISHING OF BEST FITTING ELLIPSOID**

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#### **OVERVIEW OF PREVIOUS LECTURE**

WHAT IS HEIGHT?



WHAT IS A HEIGHT SYSTEM?

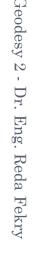
**VERTICAL DATUM** 

**COMMON HEIGHT** SYSTEMS

**HEIGHT DETERMINATION USING GRAVITY OBSERVATIONS** 

INTERNATIONAL HEIGHT REFERENCE SYSTEM (IHRS)

**ONLINE RESOURCES** 









#### **OVERVIEW OF TODAY'S LECTURE**

**DEFINITION OF GEODETIC DATUM** 



WHAT IS MEANT BY "BEST FITTING"?

**BEST FITTING DATUM AND HOW TO ACHIEVE IT IN PRACTICE** 

**NOTES ON ESTABLISHMENT OF BEST FITTING DATUM** 

SIGNIFICANCE OF ACCURATE GEODETIC DATUM

SUMMARY





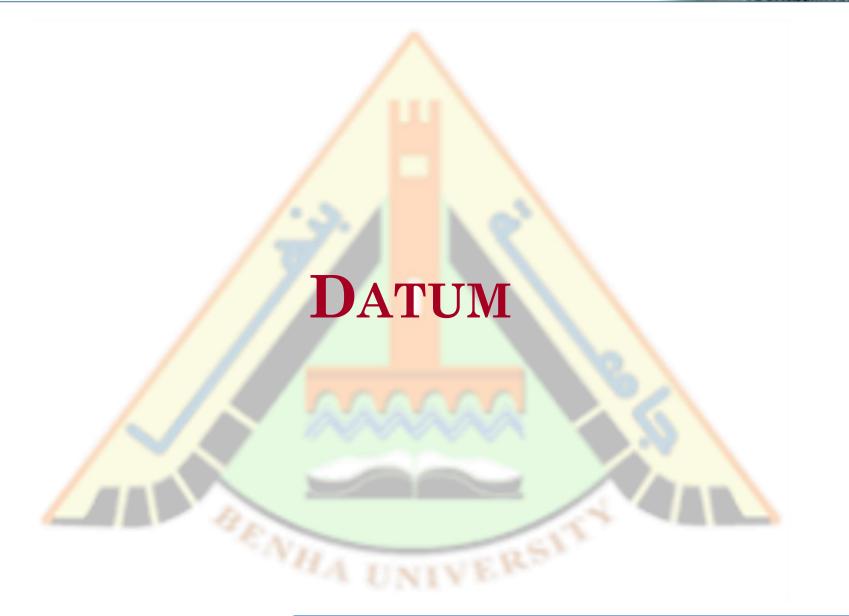
### **EXPECTED LEARNING OUTCOMES**

- Learn about geodetic datum
- Identify different types of datums.
- Gain knowledge about the main steps of establishing a local best fitting datum.
- Learn about some major applications of geodetic datums.



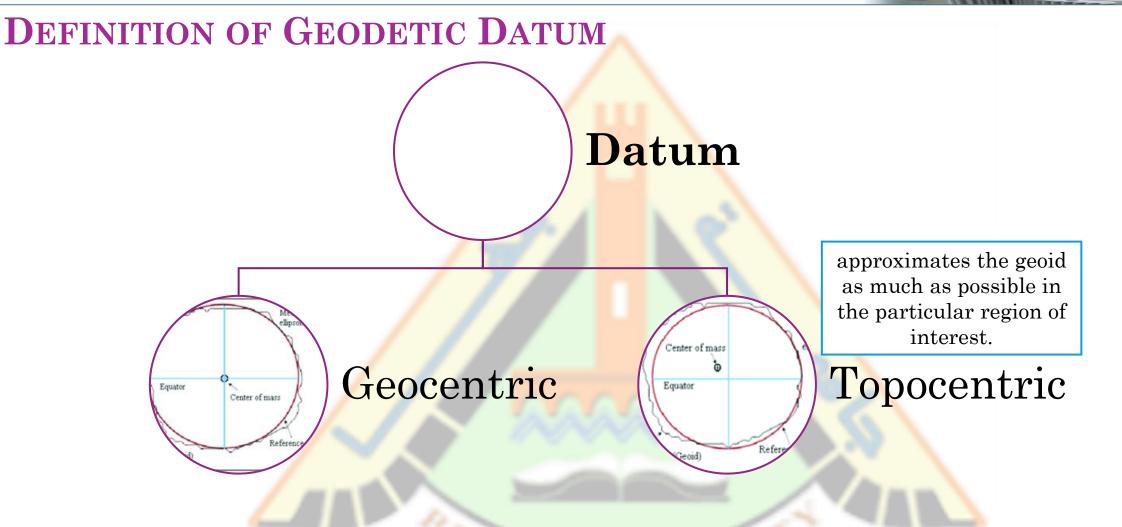












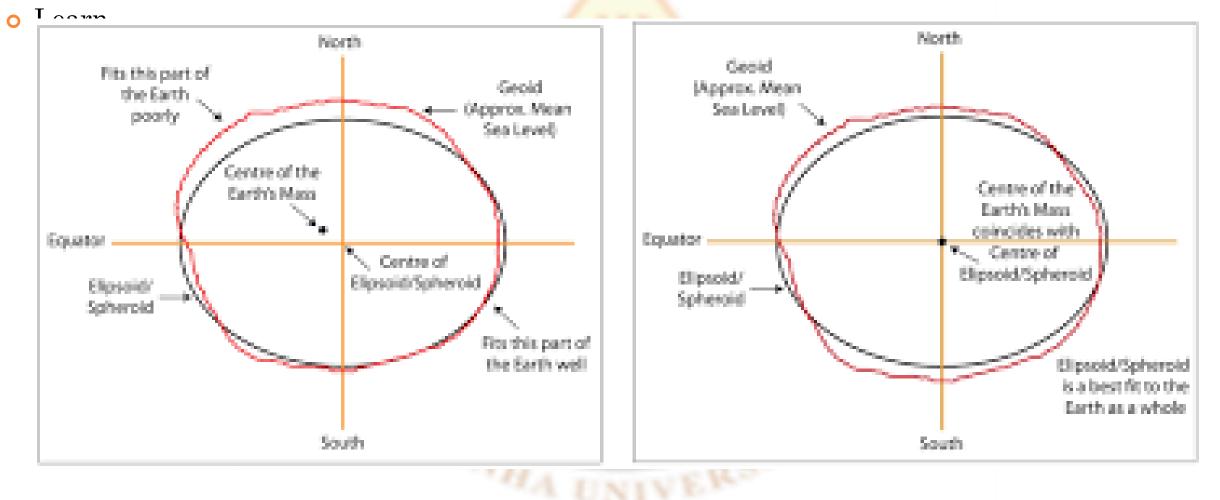
In this lecture, horizontal datum will be discussed in the context of best-fitting.







#### **DEFINITION OF GEODETIC DATUM**













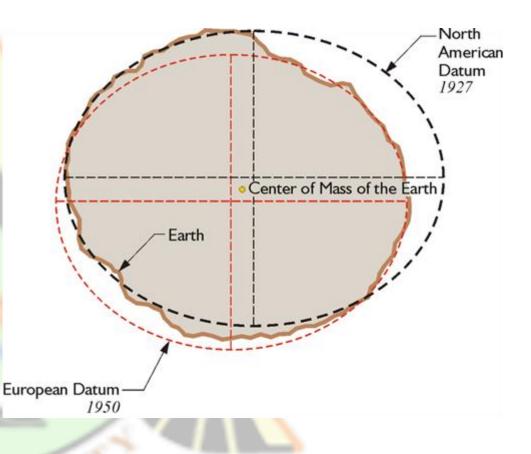
#### **BEST FITTING GEODETIC DATUM**

• The main objective of using a regional datum is to get

minimum deviations between the geoid and reference

ellipsoid over the area in question.

- When we achieve such an objective, we say that we have obtained a "best fitting ellipsoid" or a "best fitting datum", e.g., for our country.
- An ellipsoid that fits the geoid very well in a certain country does not necessarily fit in other country.









### **BEST FITTING DATUM AND HOW TO ACHIEVE IT IN PRACTICE**

#### **ASTRO-GEODETIC DATUM**





#### **BEST FITTING DATUM – FLOWCHART**

Selection of Stations

Datum Adjustment and Parameter Estimation

Selection of initial point

Observations (Triangulation, Trilateration, or hybrid)

Astronomical Observations







#### **BEST FITTING DATUM**

#### • Assumptions

The problem of determining the datum positional parameters at the initial point is solved temporarily by assuming the ellipsoid and geoid to be tangent at the initial point as a preliminary orientation and use the astronomic observations to fix the other parameters at the initial point.



The Monument at the Initial Point of NAD27





- Select the position of the datum initial point "i" (starting point of the network) to be in the 1) geometrical center of the region of interest, and having a rigid terrain surrounded by areas of modest variations in gravity.
- Select a reference ellipsoid, among the large list of ellipsoids used in practice, and specify the 2) values of two parameters defining its size and shape (e.g. a and f).
- Perform the preliminary orientation of the selected ellipsoid at the datum initial point, by setting : 3)

 $\xi_i = \eta_i = N = 0$ , and use the astronomic measurements to determine the geodetic coordinates of the initial point, as well as the geodetic azimuth of one initial line, i.e. =  $\phi_i = \Phi_i$ ,  $\lambda_i = \Lambda_i$  and  $\alpha_{ii} = \Lambda_{ii}$ .



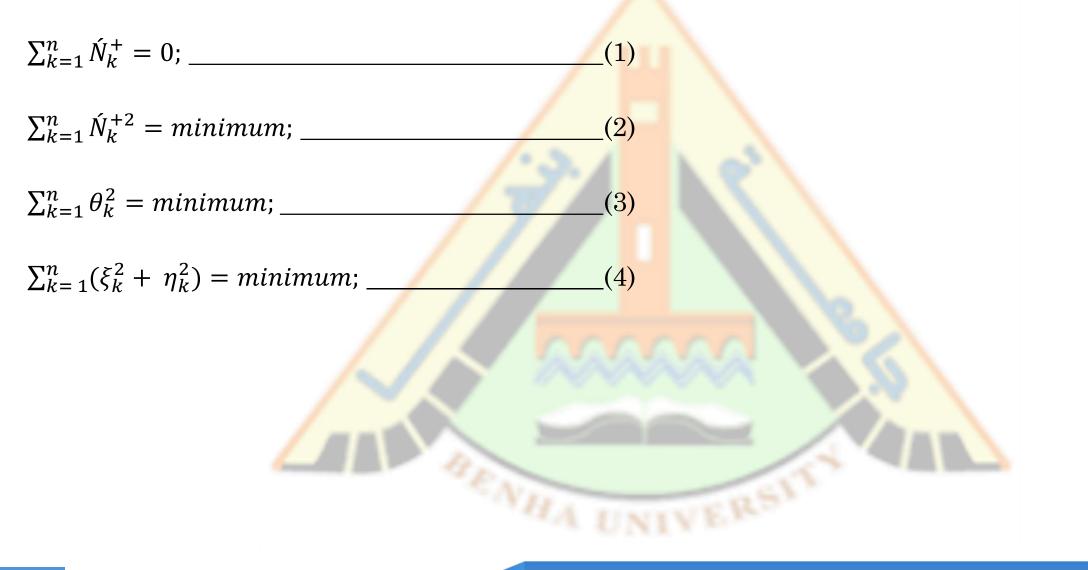


- Form the observation equations for directions azimuths and distances for the network (taking the 4) appropriate weights of observations into account), and perform a least-squares rigorous adjustment ending-up with the adjusted values of the network coordinates  $\varphi$  and  $\lambda$ .
- Measure the astronomic latitude  $\Phi_k$  and astronomic longitude  $\Lambda_k$  at all points "k" of the network, 5) i.e. k = 1, 2, ..., n where n is the number of points in the network. Then, using these measurements and their corresponding geodetic coordinates, compute the astro-geodetic geoid (i.e., the deflection components  $\zeta$ ,  $\eta$ , N).
- Select one of the conditions of minimizing the deviations between the reference ellipsoid and the 6) geoid as follows: -





#### **BEST FITTING DATUM – SUMMARIZED STEPS**







#### **BEST FITTING DATUM – SUMMARIZED STEPS**

7) Denote the observed (i.e. computed) astro-geodetic deflection components, obtained from geodetic and astronomic coordinates, by just  $\zeta_k$  and  $\eta_k$ , we can write the following expressions:

$$\zeta_k^- = \zeta_k + d\zeta_k \tag{5}$$

 $\eta_k^- = \eta_k + d\eta_k \_$ 

where  $\xi_k$  and  $d\xi_k$  are the changes required to be applied to the observed deflections  $(\xi_k, \eta_k)$  to make the sum of their squares a minimum and provide a best fitting ellipsoid. These changes, e.g.  $d\xi_k$ ,  $d\eta_k$  can be expressed as a function whose main arguments are the required changes in the ellipsoid size and shape parameters (a, f) and the independent three positional parameters  $(\xi_i, \eta_i, N_i^*)$  which were incorrectly specified to be zeros at the datum initial point. Such a function can be simply expressed as follows:

$$d\xi_{k} = F1(d\xi_{i}, d\eta_{i}, dN_{i}^{*}, da, df)$$
(7)  
$$d\eta_{k} = F1(d\xi_{i}, d\eta_{i}, dN_{i}^{*}, da, df)$$
(8)

(6)







8. We can write these two equations for  $d\xi_k$  and  $\eta_k$  For all stations having observed astro geodetic deflections "k",  $k = 1, 2 \dots n$ , in matrix notation as:

V = AX + L, \_\_\_\_\_(9)

where

- V: is the vector of deflection components after minimization.
- L: is the vector of astro geodetic deflection components before minimization (i.e. computed from astro-observations.
- X : is a vector of five unknown components which are the two corrections to the chosen ellipsoid (*da*, *df*) and three corrections to the assumed deflection components and geoid undulation at the datum initial point ( $d\xi_i$ ,  $d\eta_i$ , dN).
- A :is known as the coefficient matrix of the unknown parameters X.





- Apply the parametric least-squares estimation procedure on Equation 9, which can be considered 9. as an observation equation. The least-squares condition in this case will be:
- $V^T P V = minimum$ , (10)
- where P is the weight matrix of the observed astro-geodetic deflection components.
- Equation 10 satisfies Equation 4 which is the condition for getting a best-fitting ellipsoid.







- 10. Substituting from Equation 9 into Equation 10 and perform the minimization process, we finally
  - end-up with the following solution vector X of the required corrections to the five previously

stated unknown parameters, which is :

 $X = (ATPA)^{-1} (ATPL)$ (11)

Add the components of X-vector, as obtained from the last equation, to the assumed approximate values of the five parameters, and get the new best fitting values for  $(\phi_i, \lambda_i, N_i)$  of the initial point, as well as *a*, *f*.







## SIGNIFICANCE OF ACCURATE GEODETIC DATUM







#### SIGNIFICANCE OF ACCURATE GEODETIC DATUM

- Foundation for Precise Positioning (Surveying and Mapping, Navigation, and Remote sensing)
- Geodynamics and Plate Tectonics
- Sea Level Monitoring
- Climate Change Research
- Facilitating Infrastructure Development
- International Collaboration and Data Sharing
- Economic Benefits (Efficient Land Management, Resource Exploration, and Improved Infrastructure Investment)





#### **END OF PRESENTATION**

# **THANK YOU FOR ATTENTION!**

